

## M229 Advanced Topics in MRI Shu-Fu Shih, Ph.D. 4/29/2025

# Compressed Sensing MRI

## Today's topics

- k-Space properties review
- Compressed sensing MRI (with code examples)
  - Sparse representation
  - Incoherent artifacts
  - Nonlinear reconstruction
- Compressed sensing MRI applications

## MR acceleration

- MRI acquisition time is limited by
  - MRI physics (encoding mechanisms, relaxation properties...)
  - Hardware constraints (gradient switching...)
- Shorter MRI scan time can
  - Improve patient comfort
  - Reduce occurrence of motion artifacts
  - (from a hospital's view) Increase throughput with better resource management

Why does it take so long?



## MRI acceleration

- Different acceleration strategies:
  - (1) Sequence design: Using a rapid acquisition strategy (e.g., EPI and spiral imaging)
  - (2) Simultaneous multi-slice (SMS) techniques: Using specialized RF pulses to excite multiple slices at the same time, followed by advanced reconstruction
  - (3) Data undersampling with advanced reconstruction:
    - a. Partial Fourier reconstruction: Using conjugate symmetry in k-space
    - b. Parallel imaging: Using sensitivity information from multiple coils
    - c. Compressed sensing: Using sparsity constraints for reconstruction
    - d. Deep learning: Using non-linear neural network trained with large datasets
  - acceleration



(4) Hybrid techniques: Combining different acceleration strategies to achieve robust

https://mriquestions.com/echo-planar-imaging.html



## MRI acceleration

- Different acceleration strategies:

  - multiple slices at the same time, followed by advanced reconstruction
  - (3) Data undersampling with advanced reconstruction:
  - acceleration





• (1) Sequence design: Using a rapid acquisition strategy (e.g., EPI and spiral imaging) Will be covered on 5/8 - 5/20

(2) Simultaneous multi-slice (SMS) techniques: Using specialized RF pulses to excite



(4) Hybrid techniques: Combining different acceleration strategies to achieve robust

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## MRI acceleration

- Different acceleration strategies:

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(2) Simultaneous multi-slice (SMS) techniques: Using specialized RF pulses to excite

These techniques all require some prior information for image reconstruction

d. Deep learning: Using non-linear neural network trained with large datasets

(4) Hybrid techniques: Combining different acceleration strategies to achieve robust

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## Images with the same undersampled k-space data



Use prior information about the images to help us solve the underdetermined problem



## **Compressed sensing MRI**

- Compressed sensing MRI can reconstruct an image with high fidelity from undersampled k-space data given
  - (1) the image has transform sparsity (or a sparse representation in some transform domain)
  - (2) the k-space sampling pattern generates incoherent artifacts in the sparse transform domain
- Compressed sensing MRI usually involves a nonlinear reconstruction method to recover the image



- Many images have a sparse representation in some transform domain
- Example 1: Discrete cosine transform (DCT)
  - JPEG uses DCT for image compression

Original image

2D DCT coefficients





# $X_k = \sum_{n=0}^{N-1} x_n \cos\left[\frac{\pi}{N}\left(n + \frac{1}{2}\right)k\right] \qquad for \ k = 0, \dots N-1$

Compressed image (3.7-fold) by preserving large DCT coefficients



See code example 01





- Example 2: Wavelet transform
  - JPEG 2000 uses Wavelet transform for image compression

### Original image



### 2D Wavelet coefficients





### Compressed image (5.3-fold) by preserving large Wavelet coefficients



See code example 02





Example 3: Wavelet transform for a brain image 

Original image







#### 2D Wavelet coefficients

#### Compressed image (4.8-fold) by preserving large Wavelet coefficients



See code example 03





#### Many (MRI) images have a sparse representation in some transform domain

### Brain image



### 2D Wavelet coefficients of a brain image









Noisy image

#### 2D Wavelet coefficients of a noisy image



Not so sparse...

<u>See code example 04</u>



- - data will more likely be one that has a sparse representation



How does this "prior information" can help in image reconstruction problem?

• When the reconstruction problem is under-determined, the corresponding artifact-free or fully sampled image that best matches the undersampled



## Incoherent artifacts

- The second requirement for compressed sensing MRI:
  - sparse transform domain
- What are incoherent artifacts?
  - Noise-like or diffuse image artifacts that lack a clear, structured, or predictable pattern

The undersampling pattern should generate incoherent artifacts in the

## Incoherent artifacts

## Using the point spread function to analyze



(Figure from: Lustig et al., MRM 2007)



## Incoherent artifacts



Inverse Fourier transform



Fourier transform

## Image domain



Equidistance vs. Random undersampling





mages from equidistance undersampling



#### Wavelet transform



Inverse Wavelet transform

## Wavelet domain















#### <u>See code example 05</u>



## LO, L1 and L2 norm

Vector norm: a method to measure the length of a vector 

- L0 norm (  $\| x \|_{0}$ ): number of non-zero entries
- L1 norm (  $\| x \|_{1}$ ): sum of absolute values of the entries  $|| x ||_{1} = |x_{1}| + |x_{1}|$ • L2 norm (  $\| x \|_{2}$ ): square root of sum of squared values of the entries

$$\| x \|_{2} = \sqrt{|x_{1}|^{2} + |x_{2}|^{2} + \ldots + |x_{n}|^{2}}$$

$$x_2 + \ldots + x_n$$

# LO, L1 and L2 norm $v_1 = \begin{bmatrix} 5 \\ 0 \\ 0 \\ 2 \\ -3 \\ 0 \end{bmatrix} \quad v_2 = \begin{bmatrix} -1 \\ 2 \\ 3 \\ 2 \\ -4 \\ 2 \end{bmatrix}$

Two vectors with similar energy (L2 (L1 norm)

• 
$$\| v_1 \|_2 = \sqrt{38}$$
  
•  $\| v_1 \|_1 = 10$   
•  $\| v_1 \|_1 = 3$ 

• 
$$|| v_2 ||_2 = \sqrt{38}$$
  
•  $|| v_2 ||_1 = 14$   
•  $|| v_2 ||_0 = 6$ 

## • Two vectors with similar energy (L2 norm) can have different levels of sparsity



- Suppose we have a 2D vector  $x = [x_1, x_2]$
- Exercise 1:  $argmin_x$  | x |  $_2$ *s*.*t*.  $2x_2 = x_1 + 2$
- Exercise 2:  $argmin_x$   $|x|_1$ 
  - s.t.  $2x_2 = x_1 + 2$
- Example 3:  $argmin_x$   $|x|_0$ 
  - *s*.*t*.  $2x_2 = x_1 + 2$













- L2 norm minimization: Find a solution with smallest energy
- L1 and L0 norm minimization: Find a sparse solution

## Mathematical formulation

Our goal:

Find an image that has the sparsest coefficients in the Wavelet domain and the image is consistent with the undersampled k-space data

Turn into an optimization problem





Convex relaxation <u>using L1 norm</u>



 $argmin_{r}$ 





## Mathematical formulation

 $argmin_{x}$  | Wx

subject to  $\|Fx - y\|_{2} < \epsilon$ 

## Use Lagrangian form



## Explicitly include an sampling operator



- W: Wavelet transform operator
- x: reconstructed image
- F: Fourier transform operator
- y: acquired undersampled k-space data
- $\lambda$ : regularization parameter
- U: k-space sampling pattern

argmin<sub>x</sub>  $\|Fx - y\|_{2}^{2} + \lambda \|Wx\|_{1}$ 

 $argmin_{x} \| UFx - y \|_{2}^{2} + \lambda \| Wx \|_{1}$ 



## Mathematical formulation

 $argmin_{x}$  | Wx

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## Use Lagrangian form



## Explicitly include an sampling operator



 $argmin_{x}$ 

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argmin<sub>x</sub>  $\|Fx - y\|_{2}^{2} + \lambda \|Wx\|_{1}$ 

## $UFx - y \parallel \frac{2}{2} + \lambda \parallel Wx \parallel \frac{1}{2}$

## **Cost function**



# **Optimization algorithm**

- Solving min  $\|UFx y\|_{2}^{2} + \lambda \|Wx\|_{1}$  is non-trivial since the cost function is not smoothed at Wx=0
- Different approaches have been used to solve min  $\|UFx y\|_{2}^{2} + \lambda \|Wx\|_{1}$ 
  - Conjugate gradient descent<sup>1</sup>
  - ADMM<sup>2,3</sup>
  - Primal-dual algorithm<sup>4</sup>



[1] Lustig et al., Magn Reson Med. 2007;58(6):1182-95 [2] Wang et al., SIAM J Imag Sci. 2008;1(3):248-72 [3] Ramani et al., IEEE Trans Med Imaging. 2011;30(3):694-706 [4] Chambolle et al., J Math Imaging Vision. 2011;40(1):120-45



# Optimization algorithm

Conjugate gradient descent

$$argmin_m \quad f(m) = \| UFm - y \|_2^2 + \lambda$$

% Initialization  $k = 0; m = 0; g_0 = \nabla f(m_0); \Delta m_0 = -g_0$ % Iterations while  $(||g_k||_2 < \text{TolGrad and } k > \text{maxIter})$  { % Backtracking line-search t = 1; while  $(f(m_k + t\Delta m_k) > f(m_k) + \alpha t \cdot Real(g_k^*\Delta m_k))$  $\{t = \beta t\}$  $m_{k+1} = m_k + t\Delta m_k$  $g_{k+1} = \nabla f(m_{k+1})$  $\gamma = \frac{||g_{k+1}||_2^2}{||g_k||_2^2}$ 1156112  $\Delta m_{k+1} = -g_{k+1} + \gamma \Delta m_k$ k = k + 1



## *Wx*

 $g_k$ : gradient at k<sup>th</sup> iteration  $m_k$ : updated image result at k<sup>th</sup> iteration TolGrad: stopping criteria MaxIter: stopping criteria on iterations  $\alpha$ ,  $\beta$ : line search parameters

From: Lustig et al., MRM 2007



 Let's run code to reconstruct images using compressed sensing... (see <u>code example 06</u>)





**Zero-filled** 



Compressed sensing reconstruction

## **Compressed sensing MRI**

- Compressed sensing MRI can reconstruct an image with high fidelity from undersampled k-space data given
  - (1) the image has transform sparsity (or a sparse representation in some transform domain)
  - (2) the k-space sampling pattern generates incoherent artifacts in the sparse transform domain
- Compressed sensing MRI usually involves a nonlinear reconstruction method to recover the image



# Choice of regularization parameters argmin<sub>x</sub> $\| UFx - y \|_{2}^{2} + \lambda \| Wx \|_{1}$

- Many compressed sensing methods require tuning of regularization parameters. Larger weights on the sparsity term (larger  $\lambda$ ):
- Better suppression on noise or artifacts / Improved perceived SNR
  - appearance
- The regularization parameter is dataset-dependent.
- Methods for automatic regularization parameters selection have been investigated.

Features more likely to be over-smoothed / Resulting in images with artificial



# **Compressed sensing + Parallel imaging**

- SENSE reconstruction)
- Compressed sensing: Use sparsity constraints
- Combination of these two techniques:

Coil sensitivity maps



Coil combined image

Multi-coil k-space data

## • Parallel imaging: Use information from multiple coils (e.g., coil sensitivity in

# $argmin_{x} \| UFSx - y \|_{2}^{2} + \lambda \| Wx \|_{1}$

# **Compressed sensing + Parallel imaging**

- Sampling trajectory:

  - The fully sampled region can be used to estimate coil sensitivity maps The overall sampling scheme needs to generate incoherent under sampling artifacts





## Coil compression

- A problem in applying compressed sensing reconstruction in some applications is the increased memory requirement and computational complexity due to a large number of coils.



**Reference (32 coil elements)** 

Coil-compressed image (6 virtual coils)



• Coil compression (e.g., singular value decomposition-based technique) can be used to reduce the number of coils before compressed sensing reconstruction.



(Figures from: Zhang et al., MRM 2013)



- T<sub>2</sub> values in the knee cartilage have been used to detect disease and treatment changes in articular cartilage.
- T<sub>2</sub> quantification in the knee cartilage can help depict early cartilage degeneration.
- Challenges: Conventional multi-echo spin echo-based sequences are slow





Figure from previous lecture slide



- Acceleration strategies
  - (1) Use a faster sequence: DESS (double/dual echo steady state)
  - (2) Use compressed sensing to accelerate

An extension to the gradient-spoiled GRE which acquires both SSFP-FID and SSFP-Echo



Cost functio argmu

The difference between the two contrasts can be used to quantify  $T_2$ (figure from Hargreaves et al., JMRI 2012)

Variable density sampling



- U: k-space sampling pattern
- F: Fourier transform operator
- S: coil sensitivity maps
- x: reconstructed image
- y: acquired undersampled k-space data
- W: Wavelet transform operator
- D: total variation operator
- $\lambda_1, \lambda_2$ : regularization parameters

$$n_{x} \parallel UFSx - y \parallel \frac{2}{2} + \lambda_{1} (\parallel Wx_{fid} \parallel + r \parallel Wx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + r \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{fid} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{echo} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} (\parallel Dx_{echo} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} \parallel + \lambda_{2} (\parallel Dx_{echo} \parallel + x \parallel Dx_{echo} \parallel + \lambda_{2} \parallel + \lambda_$$



**GRAPPA 2** 7min 48 sec



FID image

> $T_2$ map

#### Compressed sensing 4min 4sec

120ms

0ms

(Figures from: Shih et al., ISMRM 2023)



- Rapid knee cartilage T<sub>2</sub> mapping

  - <u>Data sampling</u>: variable density random sampling
  - **Optimization problem**:  $argmin_{x} \parallel UFSx$
  - <u>Reconstruction</u>: non-linear conjugate gradient method

## <u>Constraint: Sparsity in Wavelet transform and sparsity in total variation</u>

$$-y \|_{2}^{2} + \lambda_{1}(\| Wx_{fid} \|_{1} + r \| Wx_{echo} \|_{1}) + \lambda_{2}(\| Dx_{fid} \|_{1} + r \| Dx_{echo} \|_{1})$$

U: k-space sampling pattern F: Fourier transform operator S: coil sensitivity maps x: reconstructed image y: acquired undersampled k-space data W: Wavelet transform operator D: total variation operator  $\lambda_1, \lambda_2$ : regularization parameters



- Cardiac cine imaging for information of the heart function throughout the cardiac cycle
- Challenges: accelerating data acquisition without compromising the high resolution and image quality requirements



(Figure from: Otazo et al., MRM 2015)



## • Sparsity in the x-f space



(Figures from: Tsao et al., JMRI 2012)



k-t sampling pattern

Raw Data



image











**k-t FOCUSS results** 

(Figures from: Tsao et al., JMRI 2012 and Jung et al., MRM 2009)



- k-t FOCUSS<sup>1</sup> (k-t FOCal Underdetermined System Solver)
  - Application: cardiac cine imaging
  - Constraint: sparsity in the x-f space
  - Data sampling: k-t undersampling
  - <u>Optimization problem</u>:  $\min_{\rho} \| y DFS\rho \|_{2}^{2} + \lambda \| \rho \|_{1}$

Reconstruction: reweighted quadratic optimization

y: acquired k-space data

- D: k-t sampling pattern
- F: Transform operator between k-space and x-f space
- S: coil sensitivity maps
- $\rho$ : reconstructed x-f space
- $\lambda$ : regularization parameter

Let  $\rho = \rho_0 + \Delta \rho$  $min_{\rho} \| y - DFS(\rho_0 + \Delta \rho) \|_{2}^{2} + \lambda \| \Delta \rho \|_{2}$ 

[1] Jung et al., Magn Reson Med. 2009;61(1):103-16







- Radial undersampling results in incoherent artifacts



Radial MRI with inherent motion robustness can be used for free-breathing MRI

(Figure from: Feng et al., JMRI 2022)



- Stack-of-radial MRI provides self-navigation to track breathing motion
- We can group the k-space data into different motion states





(Figure from: Feng et al., MRM 2016)





(Figure from: Feng et al., MRM 2016)



- using compressed sensing)
  - <u>Application</u>: free-breathing abdominal imaging
  - <u>Constraint: temporal finite differences (or total variation) in dynamic dimension</u>
  - <u>Data sampling</u>: undersampled golden-angle radial MRI
  - Optimization problem:  $min_x$
  - <u>Reconstruction</u>: non-linear conjugate gradient

XD-GRASP<sup>1</sup> (Golden-angle radial MRI with reconstruction of extra motion-state dimensions

$$FCx - y \|_{2}^{2} + \lambda_{1} \| S_{1}x \|_{1} + \lambda_{2} \| S_{2}x \|_{1}$$

[1] Feng et al., Magn Reson Med. 2016;75(2):775-88







## Compressed sensing MRI

- Limitations:
  - Requiring high computational complexity to solve the nonlinear reconstruction problem
  - Reconstruction result is dependent on the choice of regularization parameters Reconstruction may fail if the requirements are not met





## **Compressed sensing MRI**

- Conventional compressed sensing MRI requires a pre-determined sparsifying transform (e.g., Wavelet transform) for image reconstruction.
- The assumed sparsity model might not work well in certain applications.
- Attempts to move beyond this limitation...
  - <u>Dictionary-based compressed sensing MRI</u>: Using a learned dictionary of basis functions instead of a specific transform
  - <u>Low-rank based reconstruction</u>: Use the inherent redundancy and low-rank properties in (high-dimensional) MRI dataset for reconstruction
  - <u>Deep learning-based reconstruction</u>: Use the information learned from the large datasets to reconstruct undersampled MRI data



# Take home message

- 3 main components for compressed sensing MRI to work The image has a sparse representation in some transform domain • The k-space sampling trajectory generates incoherent artifacts in the sparse
- - transform domain
  - It involves a nonlinear reconstruction method

## Take home message

- (1) Can the images be sparsified in a certain (transform) domain?
  - Wavelet transform
  - Spatial total variation in images
  - Total variation in temporal frames
  - x-f space

- (2) Can the sampling pattern generate incoherent undersampling artifacts?
  - Variable density sampling pattern
  - Radial acquisition
  - Spiral acquisition

If we want to apply compressed sensing to accelerate an MRI application, check:

## Thanks!

- Next lecture
  - Fast Imaging Non-Cartesian Sampling by Dr. Wu
- See you next time
  - Deep learning MRI Reconstruction on 5/22

Questions? Contact: Shu-Fu Shih Email: sshih@mednet.ucla.edu

